

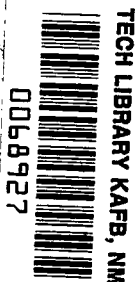
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# VISCOUS HYPERSONIC FLOW PAST A SLENDER CONE

*by V. S. Nikolayev*

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VISCOUS HYPERSONIC FLOW PAST A SLENDER CONE

By V. S. Nikolayev

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The hypersonic flow of a perfect gas at zero angle of attack past a slender cone is calculated, allowing for the transverse curvature of the surface and the interaction of the boundary layer with the shock wave. The integral relations of impulse and energy are utilized in calculating the boundary layer, assuming the profile of the longitudinal component of velocity as linear and the temperature profile as quadratic (but not similar over the length). The pressure on the external boundary of the boundary layer is determined by the Newton method, allowing for the thickness of the displaced boundary layer. The surface temperature is assumed constant (absolutely heat-conducting body).

# 1. Formulation of Problem

Consider a flow past a slender cone at zero angle of attack. Assume:  $M_\infty \gg 1$ ,  $M_\infty \theta > 1$  (where  $\theta$  is the vertex half-angle in radians),  $C_p = \text{const}$ ,  $Pr = \text{const}$ ,  $T_w = \text{const}$ , i.e., the external flow is hypersonic, the body absolutely heat-conducting, and the gas is perfect.

The equation of laminar boundary flow over the cone, taking account of the transverse curvature of the surface, has the form

$$\begin{aligned} \rho \left( u \frac{\partial u}{\partial \xi} + v \frac{\partial u}{\partial \eta} \right) &= - \frac{\partial p}{\partial \xi} + \frac{\partial}{\partial \eta} \left( \mu \frac{\partial u}{\partial \eta} \right) + \frac{\mu}{r + \eta} \frac{\partial u}{\partial \eta}, \\ \frac{\partial p}{\partial \eta} &= 0, \quad i = J C_p T, \quad p = R \rho T, \\ \rho \left( u \frac{\partial i}{\partial \xi} + v \frac{\partial i}{\partial \eta} \right) &= u \frac{\partial p}{\partial \xi} + \frac{\partial}{\partial \eta} \left( \frac{\mu}{Pr} \frac{\partial i}{\partial \eta} \right) + \frac{\mu}{Pr(r + \eta)} \frac{\partial i}{\partial \eta} + \mu \left( \frac{\partial u}{\partial \eta} \right)^2, \\ \frac{\partial}{\partial \xi} [\rho u (r + \eta)] + \frac{\partial}{\partial \eta} [\rho v (r + \eta)] &= 0. \end{aligned}$$

Here,  $\xi$  is the coordinate along the generatrix of the cone,  $\eta$  the coordinate along the normal to the surface,  $u$ ,  $v$  the velocity components in the directions  $\xi$ ,  $\eta$ , and  $r$  the local radius of the cone.

Let us determine the pressure on the body by the Newton method. If we take into account  $\delta^*$ , which is the thickness of the displaced boundary layer, then the expression for the pressure will read

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\* Numbers given in the margin indicate pagination in the original foreign text.

$$p = \rho_{\infty} u_{\infty}^2 \left( \theta + \frac{d\delta^*}{d\xi} \right)^2. \quad (1.1)$$

We note that, under the assumptions adopted,  $u_{\delta} \approx u_{\infty}$ , while  $\delta^* \approx \delta$ .

It is easy to obtain the integral relations of momentum and energy; after eliminating a number of terms - which the formulation of the problem permits - these relations take the form:

$$\frac{d}{d\xi} \int_0^{\delta} \rho u (r + \eta) (u_{\delta} - u) d\eta = \delta (r + \delta/2) \frac{\partial \rho}{\partial \xi} + r \left( \mu \frac{\partial u}{\partial \eta} \right)_w. \quad (1.2a)$$

$$\frac{d}{d\xi} \int_0^{\delta} \rho u (r + \eta) (\tau_{\delta} - \tau) d\eta = \frac{r}{Pr} \left( \mu \frac{\partial \tau}{\partial \eta} \right)_w. \quad (1.2b) \quad \text{10}$$

Here,  $\tau = i + u^2/2$ .

## 2. Approximation of the Velocity and Temperature Profiles

Let us take the profile of the longitudinal velocity component as linear, transverse to the boundary layer:

$$\frac{u}{u_{\delta}} = \frac{\eta}{\delta}. \quad (2.1)$$

Let us assume the temperature profile as quadratic:

$$\frac{i}{\tau_{\infty}} = f \left( 1 - \frac{\eta}{\delta} \right) \left( 1 + \frac{\eta}{t\delta} \right) \quad (2.2)$$

[an analogous approximation was used by Pai (Ref.1)].

In the resultant formula,  $t$  depends on  $\xi$ , i.e., there is no similarity of the temperature profile over the length, while  $f$  is the dimensionless temperature of the wall,  $f = 2i_w/u_{\infty}^2$ .

The approximation used for the velocity and temperature profiles is unsatisfactory in the case of a strongly cooled surface. For  $f \ll 1$ ,  $u$  and  $i$  cannot be represented at all in the form of simple polynomials in  $\eta$ . Let us try, for example, to satisfy the equation of influx of heat to the wall:

$$\frac{\partial}{\partial \eta} \left( \frac{\mu}{Pr} \frac{\partial i}{\partial \eta} \right) + \frac{\mu}{Pr(r + \eta)} \frac{\partial i}{\partial \eta} + \mu \left( \frac{\partial u}{\partial \eta} \right)^2 = 0.$$

Let us represent  $u$  and  $i$  in the form of series:

$$u = u_{\infty} [a_1 \eta / \delta + a_2 (\eta / \delta)^2 + \dots], \quad i = \tau_{\infty} [f + b_1 \eta / \delta + b_2 (\eta / \delta)^2 + \dots].$$

Substituting the series for  $u$  and  $i$  into the equation for the influx of heat to the wall, we obtain the following expression for  $f$ :

$$f = - \frac{0.5 b_1^2}{2 \text{Pr} a_1^2 + 2 b_2 + b_1 \delta / r}.$$

An analysis of this formula shows that, at  $f \ll 1$ , it is impossible for  $a_1$ ,  $b_1$ , and  $b_2$  to be all of the order of unity at the same time.

Thus the approximations adopted for  $i$  and  $u$  are not satisfactory for  $f \ll 1$ , although the use of the integral relations will probably permit some extension of the range of value of  $f$  at which the results of this work can be used.

### 3. Solution of the System of Equations

Substituting eqs.(2.1), (2.2) and (1.1) into eq.(1.2), we obtain a system of two second-order differential equations. At  $\xi = 0$  the equations have a singularity. Let us perform the substitution:

$$x = (\rho_{\infty} u_{\infty} \theta^4 \xi / \mu_w)^{1/4}, \quad y = \delta (\rho_{\infty} u_{\infty} / \mu_w \theta \xi^4)^{1/4}.$$

As a result, we obtain a dimensionless system of differential equations not containing singularities at  $x = 0$ :

$$\begin{aligned} y \left\{ x \frac{d}{dx} \left[ \left( 4y + 5x + x \frac{dy}{dx} \right)^2 y (Ay + Bx) \right] + 6 \left( 4y + 5x + x \frac{dy}{dx} \right)^2 y (Ay + Bx) \right\} - \\ - y^2 \left( x + \frac{y}{2} \right) \left\{ x \frac{d}{dx} \left( 4y + 5x + x \frac{dy}{dx} \right)^2 - \right. \\ \left. - 2 \left( 4y + 5x + x \frac{dy}{dx} \right)^2 \right\} - 125 = 0. \end{aligned} \quad (3.1a)$$

$$\begin{aligned} y \left\{ x \frac{d}{dx} \left[ \left( 4y + 5x + x \frac{dy}{dx} \right)^2 y (Ly + Mx) \right] + \right. \\ \left. + 6 \left( 4y + 5x + x \frac{dy}{dx} \right)^2 y (Ly + Mx) \right\} - 125 = 0. \end{aligned} \quad (3.1b) \quad \underline{11}$$

In eq.(3.1),  $A$ ,  $B$ ,  $L$  and  $M$  are functions of  $t$  at constant  $\text{Pr}$ ,  $f$  and  $\kappa$ :

$$\begin{aligned} A &= \frac{2\kappa}{f(x-1)} \left[ \frac{t}{2} - t^2 + t^3 \ln \left( 1 + \frac{1}{t} \right) \right], \\ B &= \frac{2\kappa}{f(x-1)} \left[ t - t^2 \ln \left( 1 + \frac{1}{t} \right) \right], \end{aligned}$$

$$L = \frac{2 \pi \text{Pr}}{f^2(x-1)} \left[ -t^3 + \frac{t^3}{2} - \frac{t}{3} + \frac{t(1-f)}{3(1-t)} + t^4 \ln \left( 1 + \frac{1}{t} \right) \right],$$

$$M = \frac{2 \pi \text{Pr}}{f^2(x-1)} \left[ t^2 - \frac{t}{2} + \frac{t(1-f)}{2(1-t)} - t^3 \ln \left( 1 + \frac{1}{t} \right) \right].$$

The system of equations (3.1) was solved numerically on an M-20 computer for several sets of values of  $f$  and  $\text{Pr}$ . For  $0 < x < 0.2$ , the system was solved by series, since the expressions for the derivatives, as  $x \rightarrow 0$ , are an indeterminacy of the form  $0(x^2)/0(x^2)$ . Let us represent  $y$  and  $t$  in the form of series:

$$y = y_0 + y_1 x + \dots + y_m x^m + \dots;$$

$$t = t_0 + t_1 x + \dots + t_m x^m + \dots$$

On substituting the series for  $y$  and  $t$  into eq.(3.1) and equating the coefficients of the various powers of  $x$ , we can successively determine all  $y_m$  and  $t_m$  (conventional method of indeterminate coefficients).

The first ten terms of the series were calculated. Taking account of such a large number of terms of the series is necessary to ensure a smooth transition to the numerical integration at  $x > 0.2$ . If the number of terms taken is small, the solution at  $x > 0.2$  may prove unstable, due to the small errors produced in solving the series for  $x < 0.2$ .

The formulas for determining  $y_m$  and  $t_m$  for large  $m$  are extremely unwieldy and cannot be directly programmed. We did, however, succeed in setting up a general logical scheme for calculating  $y_m$  and  $t_m$  by the method of indeterminate coefficients, without separately programming the calculation of each individual coefficient.

In the range of  $0.2 < x < 4$ , the system (3.1) was solved numerically by the Adams method with the interval  $\Delta x = 0.0005$ . As a result we obtained the relation  $y = y(x)$ , which determines the law of thickness distribution of the boundary layer along the cone, and also  $t = t(x)$ .

#### 4. Calculation of Pressure Distribution Coefficients of Frictional Drag and Heat Transfer

Knowing the relations  $y = y(x)$  and  $t = t(x)$ , we can find the thickness of the displacement  $\delta^* \approx \delta$ , the pressure distribution over the surface of the cone, the coefficient of frictional drag  $C_F$  and the coefficient of heat transfer  $C_H$ .

We introduce the quantities  $C_F$  and  $C_H$  by means of the formulas

$$C_F = \frac{X}{q_\infty \pi r_l^2}, \quad C_H = \frac{Q_w}{\rho_\infty u_\infty \tau_\infty (1-f) \pi r_l^2}.$$

Here,  $X$  is the total frictional drag,  $Q_w$  the total heat flux to the cone



surface,  $q_\infty$  the velocity head,  $r$  the maximum radius of the cone. In variables  $x, y, t$  the expressions for  $\delta, p, C_F, C_H$  are of the form: /12

$$\delta = ry/x, \quad p = \rho_\infty u_\infty^2 t^2 (1 + 0.2 dy/dx + 0.8 y/x)^2,$$

$$C_F = \frac{20 \theta^2}{\eta^{10}} \int_0^\eta \frac{x^4 dx}{y}, \quad C_H = \frac{10 \theta^2 f}{\eta^{10} \text{Pr} (1-f)} \int_0^\eta \frac{(1-t) x^4 dx}{ty}.$$

Here,  $\eta$  is the value of  $x$  at  $\xi = 1$ .

For comparison, the quantities  $p, C_F$  and  $C_H$  were also calculated without allowing for the interaction of the boundary layer with the shock wave. All other assumptions adopted in the course of this work, however, were retained.

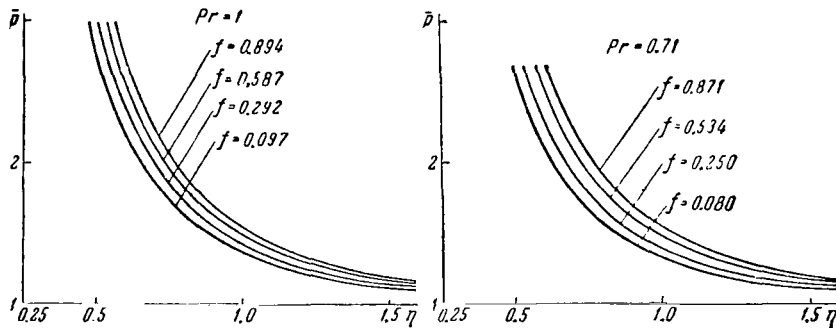


Fig.1

Figures 1 - 3 show the dependence of the relative quantities  $\bar{p}, \bar{C}_F$ , and  $\bar{C}_H$  on the interaction parameter  $\eta$ . The quantities  $\bar{p}, \bar{C}_F$ , and  $\bar{C}_H$  are the ratios of the values of  $p, C_F$ , and  $C_H$  calculated with allowance for the interaction of the boundary layer with the shock wave, to the corresponding values calculated without such allowance, and characterize the effect of the interaction.

### 5. Calculation of the Surface Temperature

The families of curves obtained at constant  $f$  permit, by the method of successive approximations, determining  $f$  itself, i.e., the surface temperature, if some method of heat removal from the surface of the body is assigned. It is not difficult to calculate the surface temperature if, for instance, the entire quantity of heat reaching the body from the gas by means of heat transfer is expended on radiation, proportional to the fourth power of the surface temperature. The equation of heat balance reads /13

$$\frac{C_H 8 (JC_p)^* \rho_\infty \theta}{\epsilon \sigma u_\infty^4} = \frac{f^4}{1-f}.$$

Here,  $\sigma$  is the Stefan-Boltzmann constant, and  $\epsilon$  is the emissivity of the surface of the body. Two or three iterations have been shown by calculations to be sufficient for the process of successive approximation.

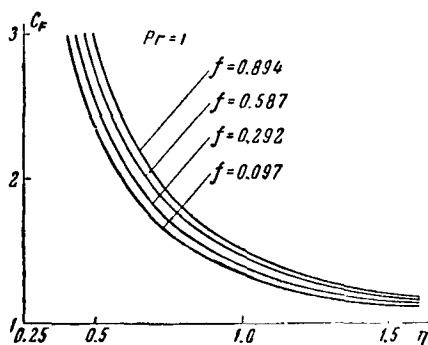


Fig.2

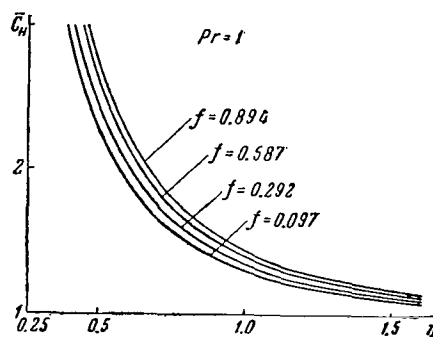


Fig.3

## 6. Limits of Applicability of the Method and a Few Conclusions

The above method permits taking account of the influence of interaction of the boundary layer over a slender cone with the shock wave in the entire range of interaction for cases of strong and weak interaction, and in the intermediate region. The fact that the method of calculation with and without allowance for the interaction is of the same kind permits the assumption that the relative quantities  $p$ ,  $\bar{C}_F$ , and  $\bar{C}_H$  are found more accurately in this work than the absolute values of the corresponding quantities, whose determination is subject to the possible influence of a large number of simplifying assumptions.

Comparisons of the results of calculations without allowance for the interaction, with the more accurate calculations of  $C_F$  and  $C_H$  have shown discrepancies as high as 10 - 15% for  $C_F$  and 30 - 40% for  $C_H$ , in a number of cases (especially at  $Pr \neq 1$ ).

The quantities  $C_F$  and  $C_H$ , however, may also be determined without allowing for the interaction; in that case, after calculating the interaction parameter  $\eta$ , these quantities can be multiplied by the relative values  $\bar{C}_F$ ,  $\bar{C}_H$ , etc., obtained in this work.

It should also be borne in mind that the boundary-layer equations used in this work are applicable with an accuracy of  $(\delta/l)^2$ , whereas the effect of slipping, in the case of  $T_w = 0(T_0)$  when it reaches a maximum is, according to estimates, of an order greater than  $\lambda_w/\delta = O(\delta/l)$  (Ref.2), where  $\lambda_w$  is the mean free path of the molecules at the wall. This imposes certain restrictions in using the results of the present work.

The method presented may find application in calculations of the flow past slender cones (with a vertex half-angle of  $\theta < 20^\circ$ ) at low Reynolds numbers in the range of flight altitudes of  $H = 50 - 100$  km and in low-density wind tunnels.

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2. Galkin, V.S.: Study of the Hypersonic Flow of a Viscous, Slightly Rarefied Gas around a Flat Plate (Issledovaniye obtekaniya ploskoy plastiny giperzvukovym potokom vyazkogo slaborazrezhennogo gaza). Izv. Akad. Nauk SSSR, Otd. Tekhn. Nauk, Mekhanika i Mashinostr., No.3, 1961.

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